

# An FPRAS for two-terminal reliability in directed acyclic graphs

Weiming Feng (ETH Zürich)

Joint work with Heng Guo (University of Edinburgh)

ICALP

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# s-t network reliability

## Two-terminal network reliability

**Input:** a graph  $G = (V, E)$  and parameters  $q_e \in (0,1)$

a source node  $s$  and a sink node  $t$

**Output:** the *probability* that  $s \rightarrow_{G(p)} t$  if each edge  $e \in E$  fails independently with prob.  $q_e$

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Exact computing is #P-complete for **directed** / **undirected** / **DAG** / **planar DAG** graphs

# Approximate s-t network reliability in DAGs

## Two-terminal network reliability approximation

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an error bound  $\varepsilon > 0$

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**Output:** a **random** number  $\hat{q}$  approximating s-t network unreliability  $1 - p$

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# Previous works

**Direct Monte Carlo** method (sample random subgraph and check reachability)

- the estimation is efficient if  $p = \frac{1}{\text{poly}(m)}$  (e.g.  $q_e = O\left(\frac{\log m}{m}\right)$  is small, where  $m = |E|$ )



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Improved analysis on lower bound of s-t reliability [[Zenklusen and Laumanns 10](#)]

- Improve the lower bound of reliability for some special DAGs

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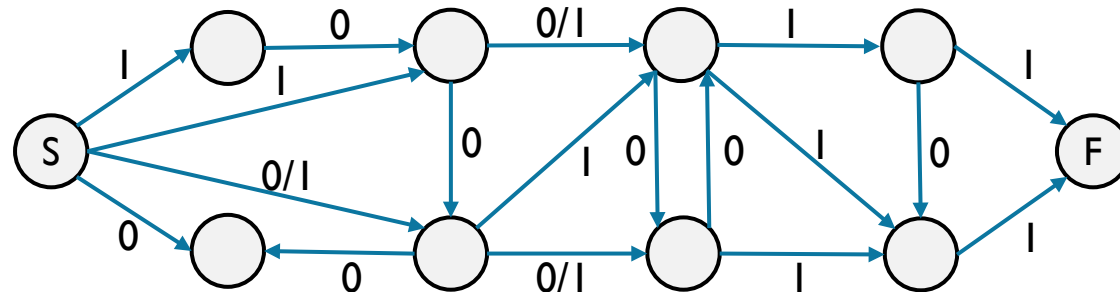
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An NFA

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  - ➡ An FPRAS for s-t reliability in DAG (running time is a huge polynomial)

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Very recently, improved FPRAS for #NFA [Meel, Chakraborty and Mathur 24]

- An FPRAS for s-t reliability in time  $\tilde{O}(m^{19})$  for  $q_e = \frac{1}{2}$  via standard black-box reduction

# Our results

There is an **FPRAS** for two-terminal network **reliability** in DAGs in time

$$\tilde{O}(n^6 m^4 \max\{m^4, \varepsilon^{-4}\}), \text{ where } n = |V| \text{ and } m = |E|$$

- technique inspired by [\[Arenas, Croquevielle, Jayaram and Riveros 21\]](#)
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There is **no FPRAS** for two-terminal network **unreliability** in DAGs unless there is an FPRAS for **#BIS** problem

**#BIS**: counting the number of independent sets in bipartite graphs  
conjectured to have no FPRAS

# Some basic settings for this talk

## Two-terminal network reliability approximation

**Input:** a **DAG (direct acyclic graph)**  $G = (V, E)$  and parameters  $q_e \in (0,1)$

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## Assumption

For any edge  $e \in E$ ,  $q_e = \frac{1}{2}$

general  $q_e \in (0,1)$  can be solved with **very small tweaks**

$$p = \frac{\#\{\text{subgraphs such that } s \text{ can reach } t\}}{2^m}$$

counting  
problem

# Sampling and counting

## Two-terminal network reliability in DAGs

$$\Omega = \{\text{subgraphs of } G \text{ such that } s \text{ can reach } t\}$$

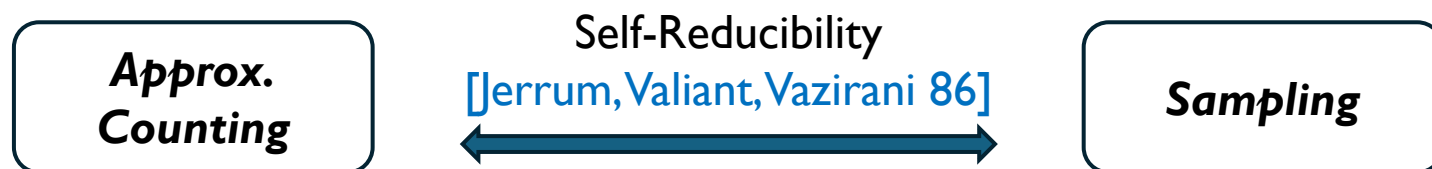
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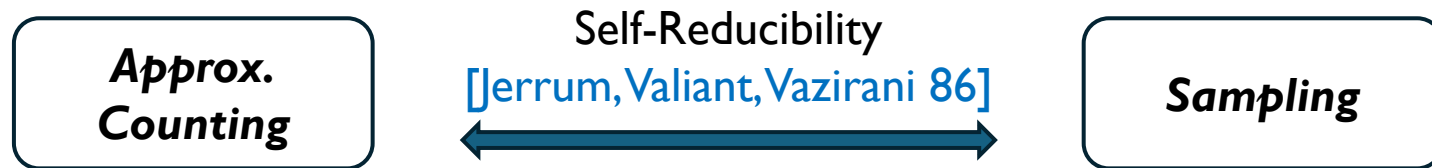


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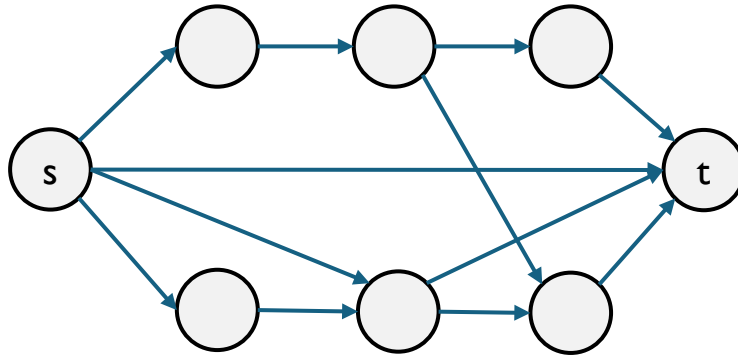
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## Our algorithm

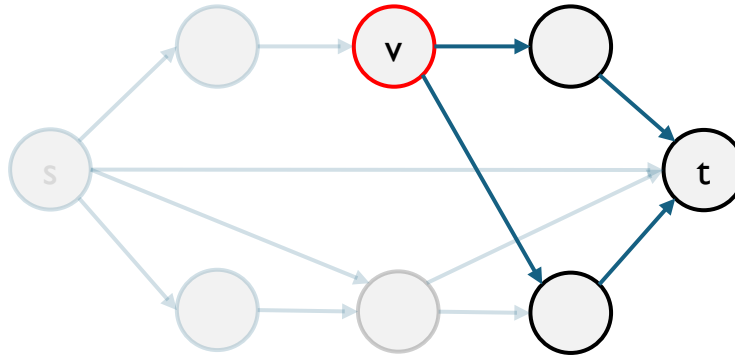
- Decompose the input two-terminal reliability instance into many **sub-instances**
- Solve the **sampling / counting** problems recursively in sub-instances

# Our Algorithm



sort all vertices according to topological order  $s = v_n \succ v_{n-1} \succ \dots \succ v_1 = t$

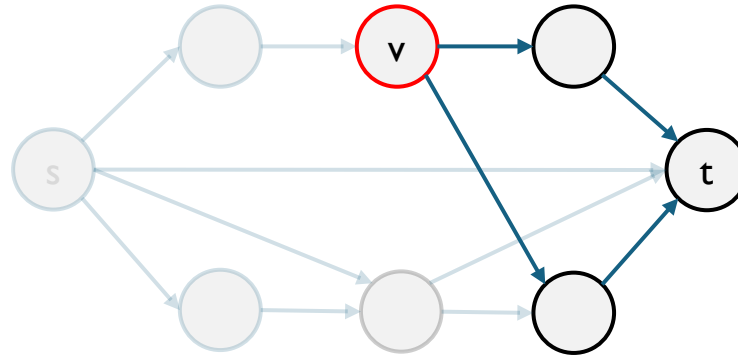
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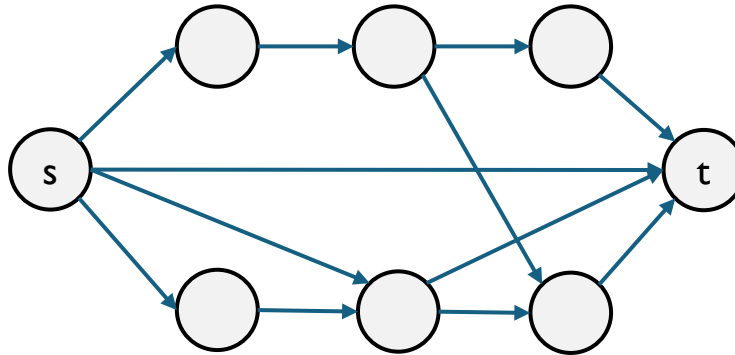
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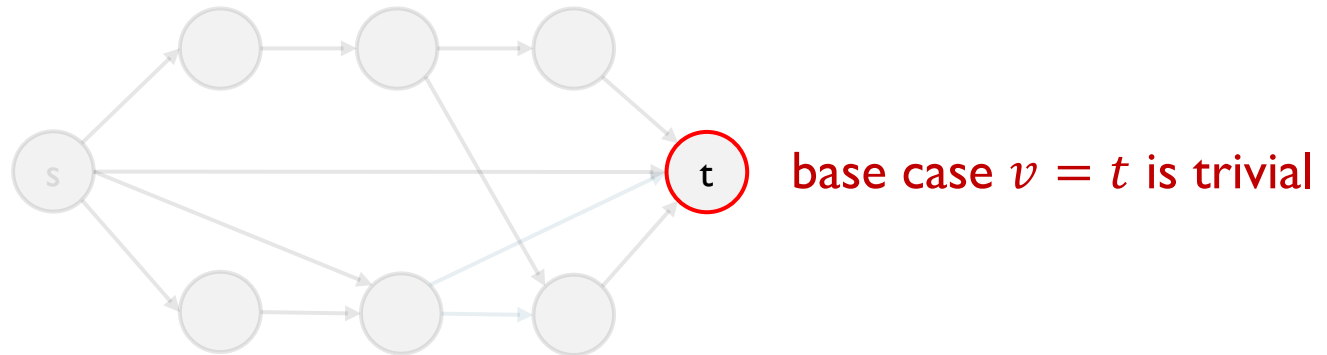
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Compute  $(Z_v, S_v)$  for  $v$  from  $v_1$  to  $v_n$  via **dynamic programming + Monte Carlo**

Framework appeared in [Gore, Jerrum, Kannan, Sweedyk, and Mahaney 97] [Arenas, Croquevielle, Jayaram and Riveros 21]



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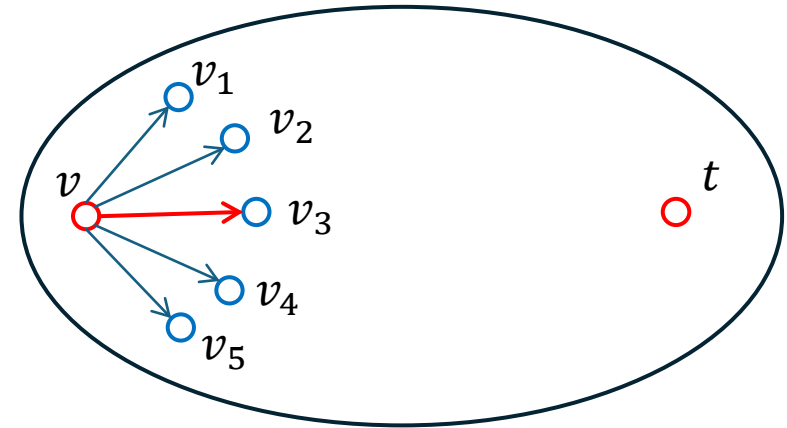
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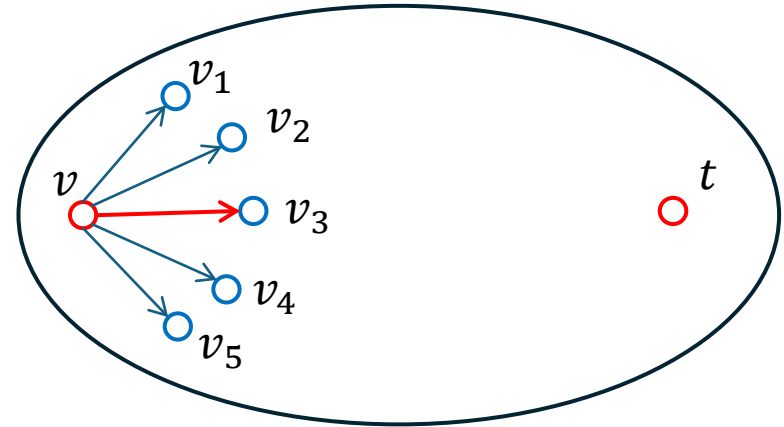
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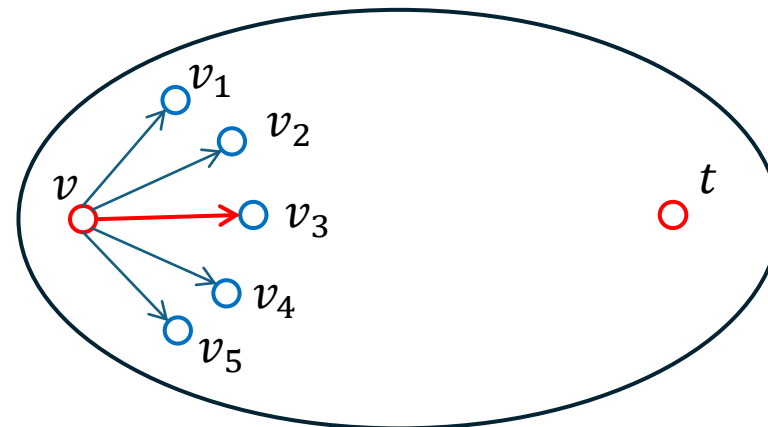
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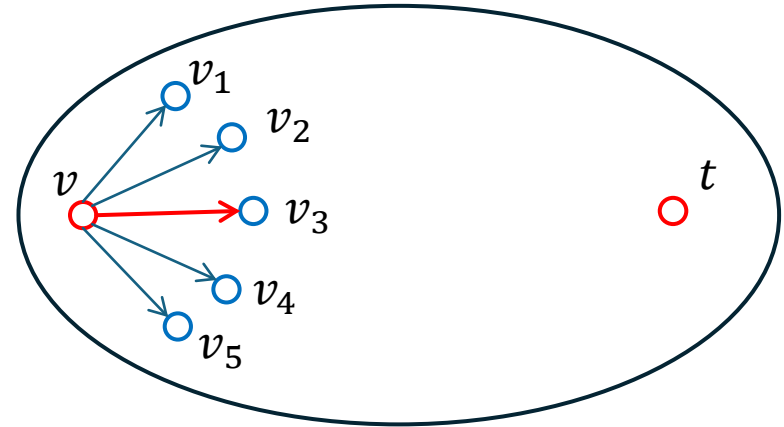
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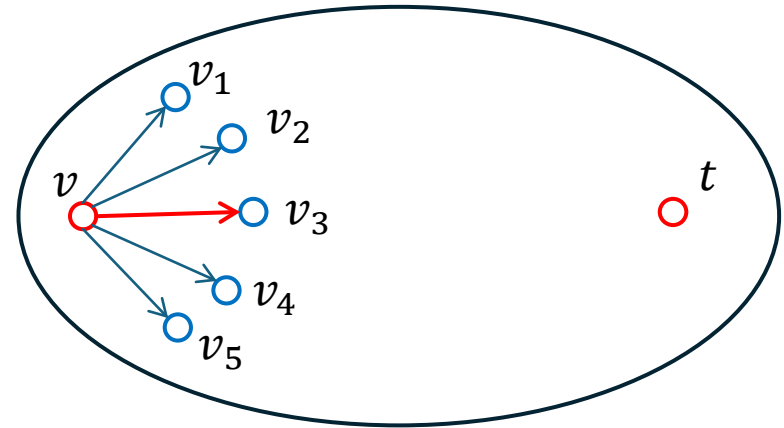
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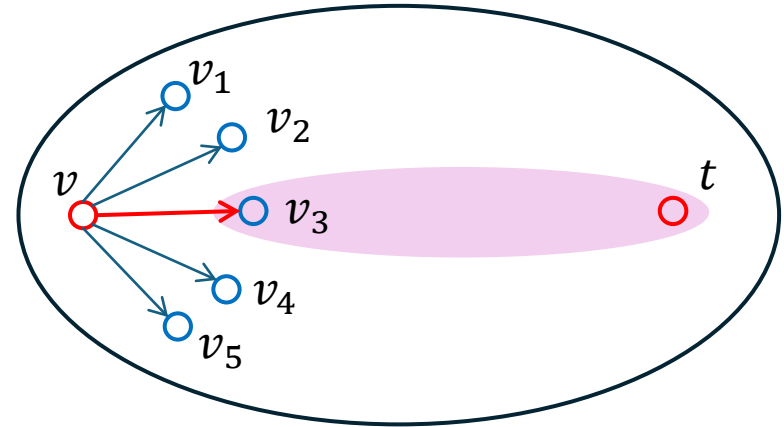
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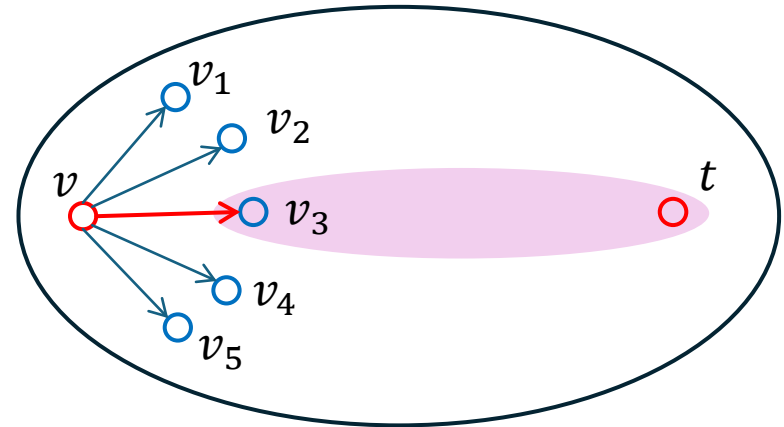
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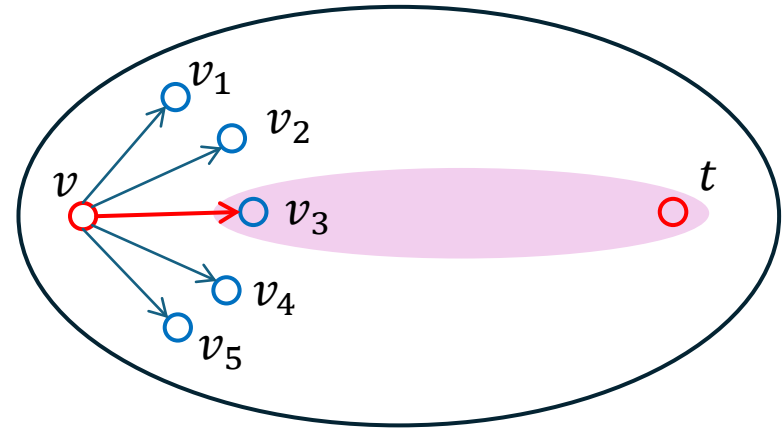
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- A vertex  $v \in V$  and a set of **neighbors**  $v_1, v_2, v_3, \dots, v_d$

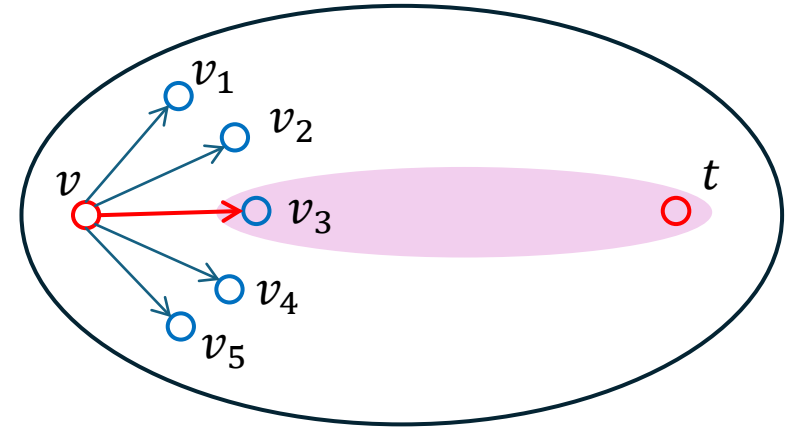
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- Vertex  $v$  must reach  $t$  through some neighbors

$$\Omega_v = \bigcup_{i=1}^d \Omega_i$$



## Karp-Luby's method for estimating the size of union [Karp and Luby 83]

- Sample an index  $i \in [d]$  with prob  $\propto |\Omega_i|$   $\rightarrow$  estimate  $|\Omega_i|$  using  $Z_{v_i} \approx |\Omega_{v_i}|$
- Sample a subgraph  $H$  from  $\Omega_i$  uniformly at random  $\rightarrow$  take a sample  $H' \in S_{v_i}$  and modify  $H' \rightarrow H$
- $X \in \{0,1\}$  indicate whether  $i$  is the first set containing  $H$   $\rightarrow$  do DFS search in  $H$

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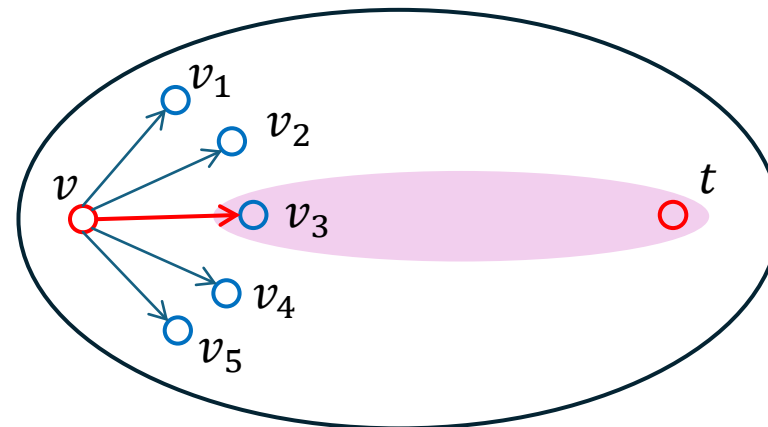
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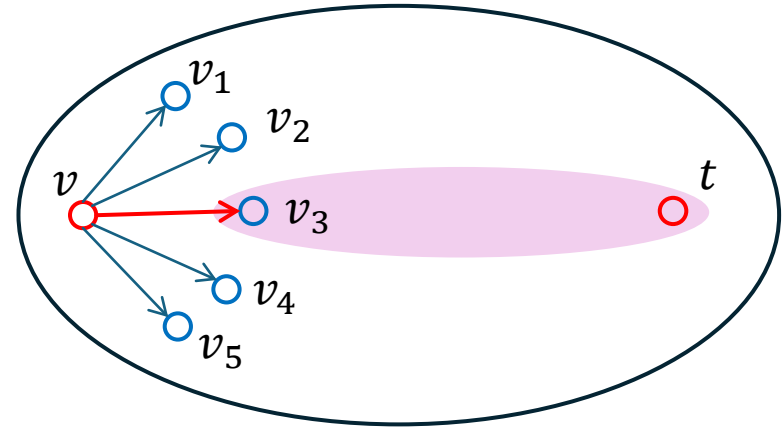
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$$2/3 \rightarrow 1 - \exp(-\text{poly}(m))$$

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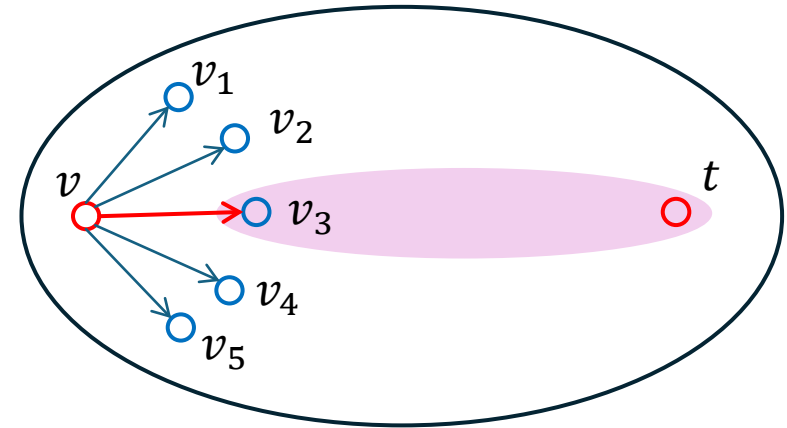
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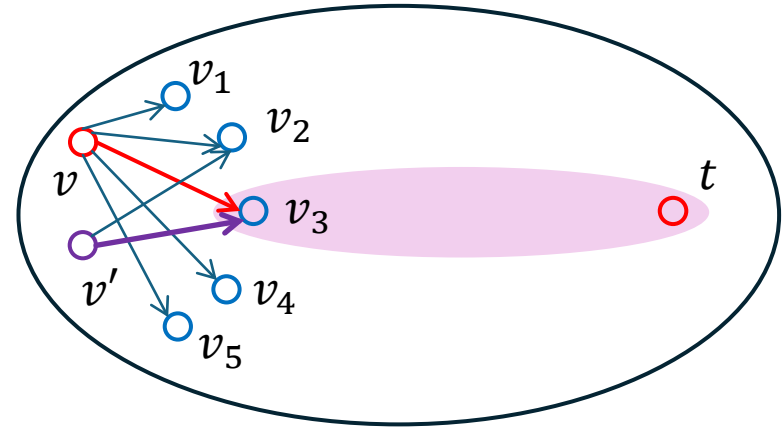
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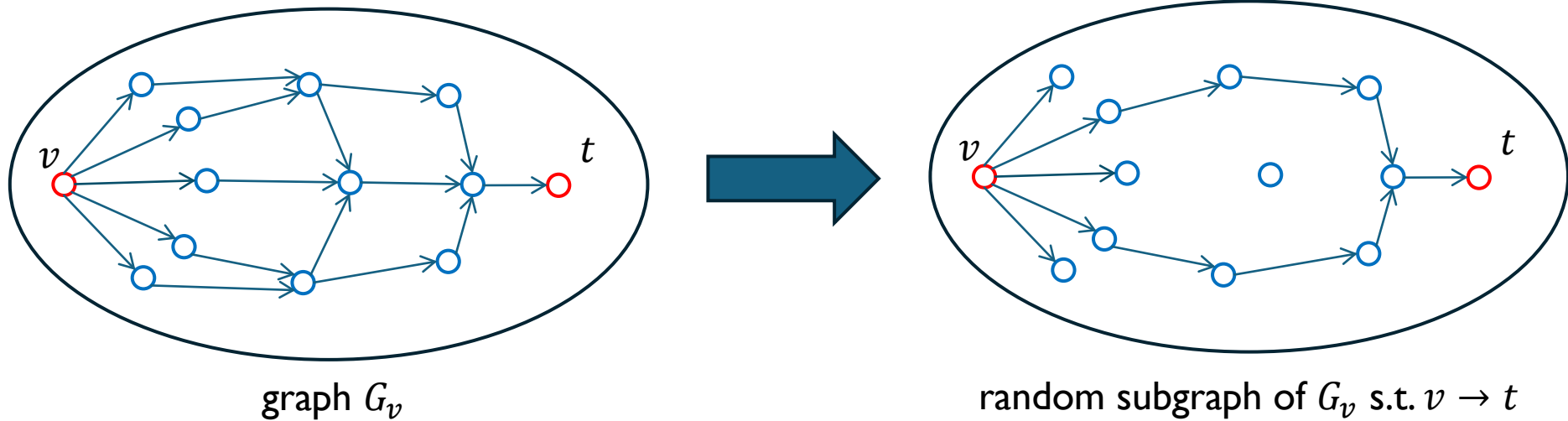
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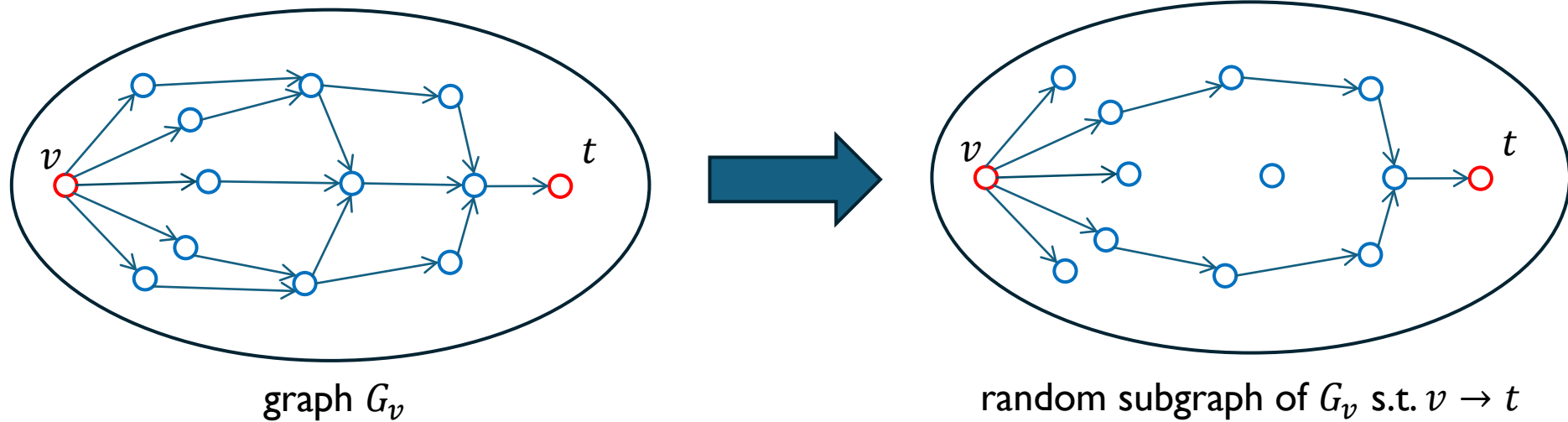
- **Higher accuracy** and **higher successful probability** require **more samples** in set  $S_{v_i}$
- Different vertices  $v, v'$  may have the same neighbor  $v_i$ , we **reuse**  $S_{v_i}$  when computing  $Z_v$  and  $Z_{v'}$

# Generate the samples via self-reduction



- Go through all edges  $e_1, e_2, \dots, e_m$  in graph  $G_v$  in some ordering

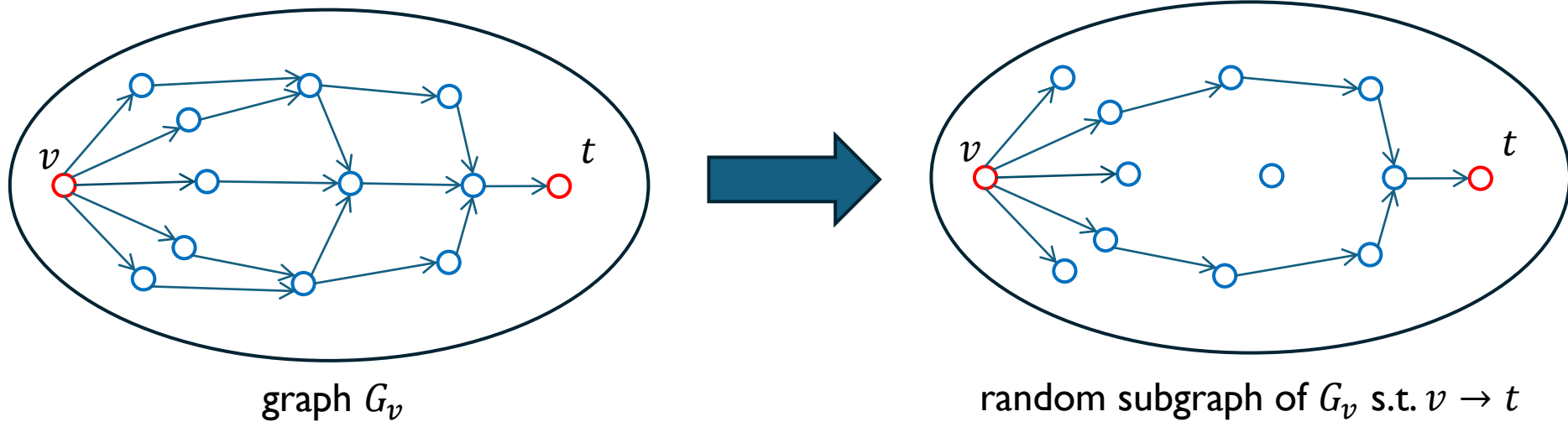
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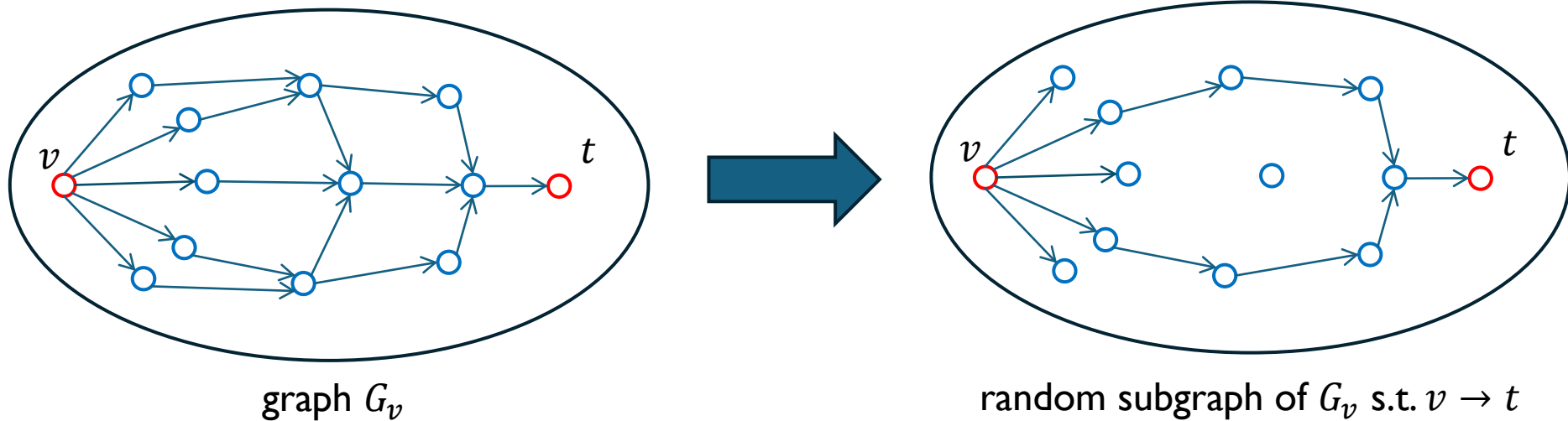
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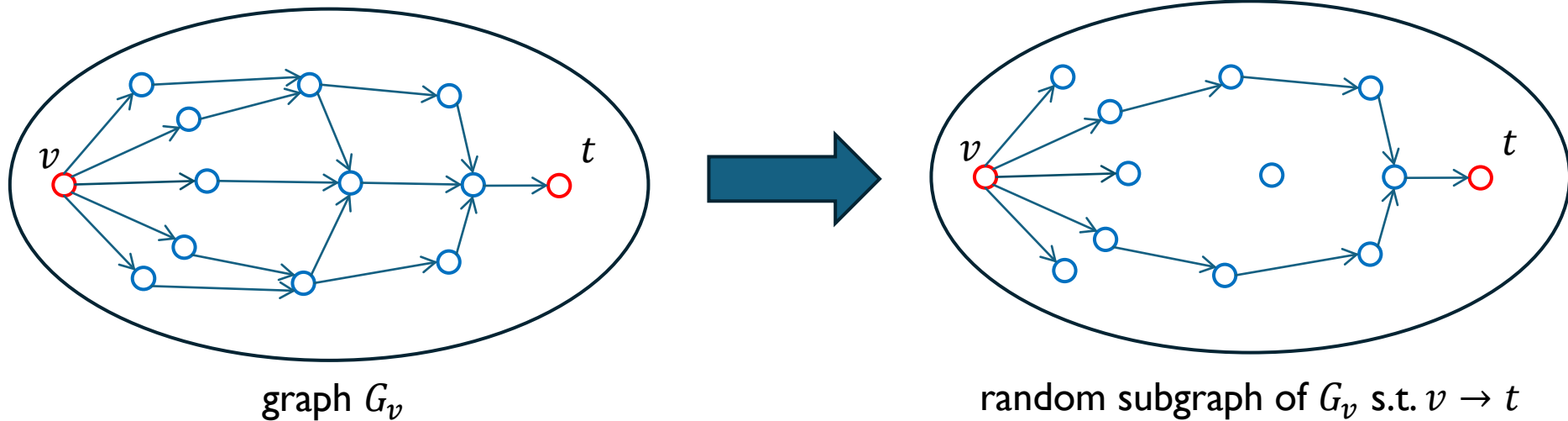


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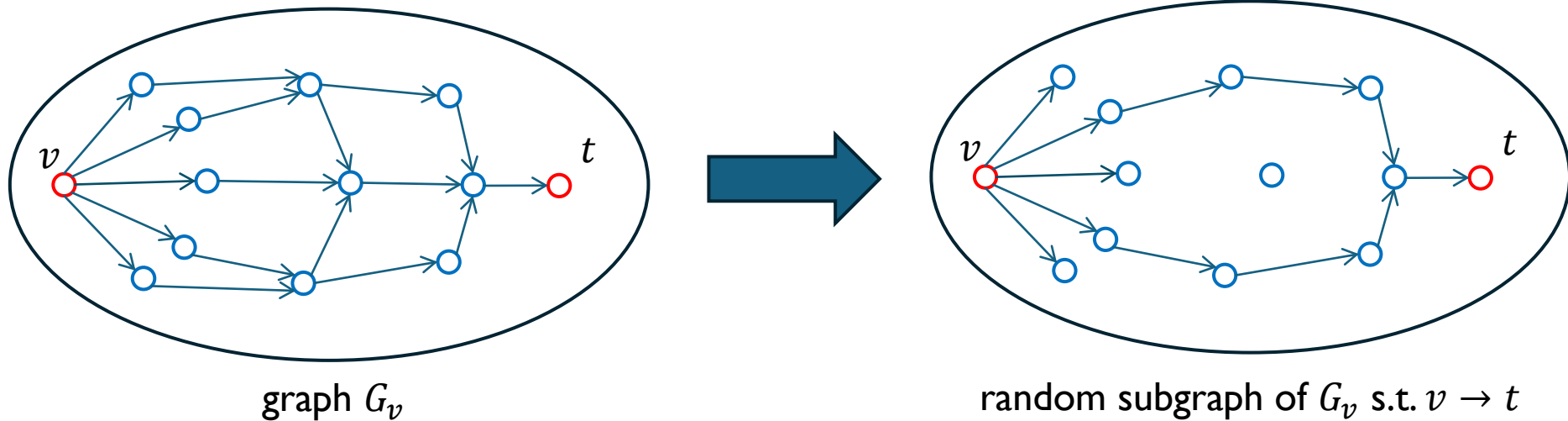


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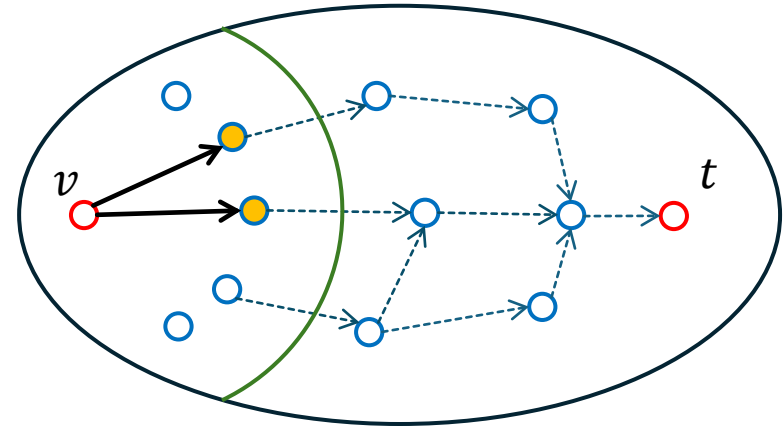


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- Suppose we have sampled  $X(e_i)$  for  $i \leq \ell$
- Let  $\mathcal{E}$  be set of edges  $e_i$  s.t.  $X(e_i) = 1$
- $\Lambda = \{w \in V : v \rightarrow w \text{ through edges in } \mathcal{E}\}$

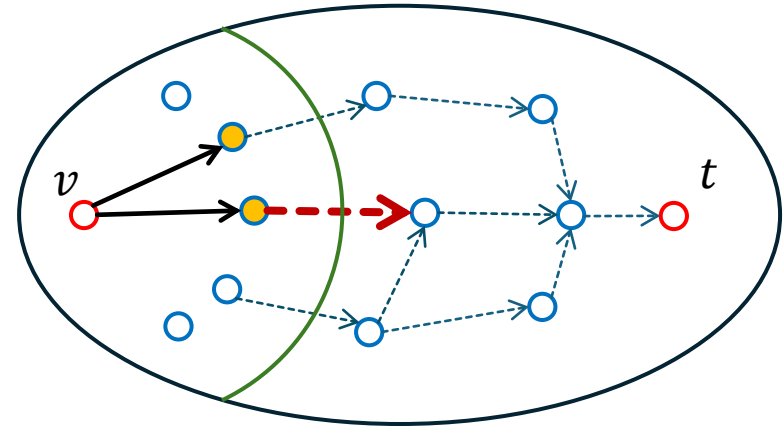
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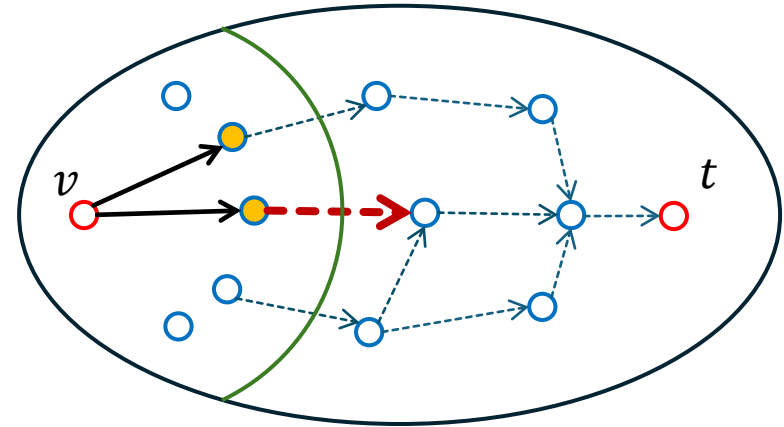
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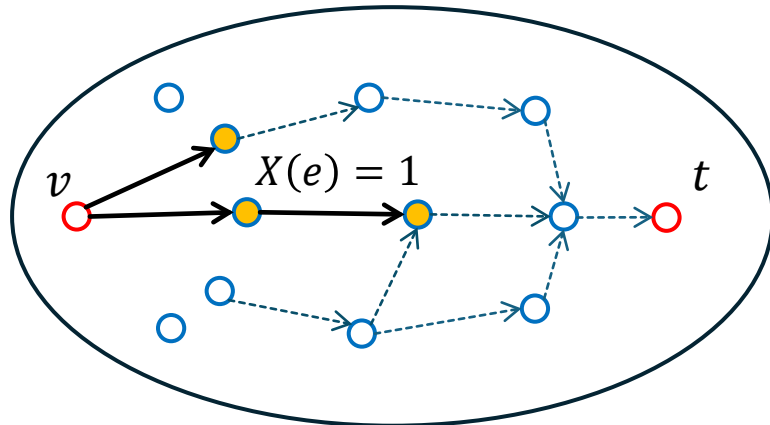
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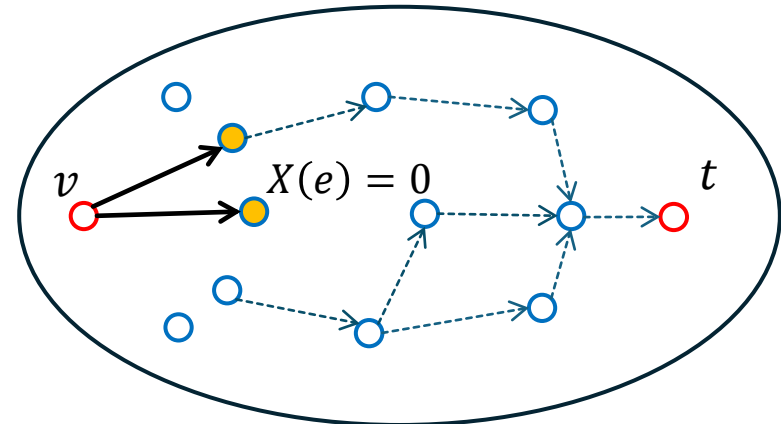
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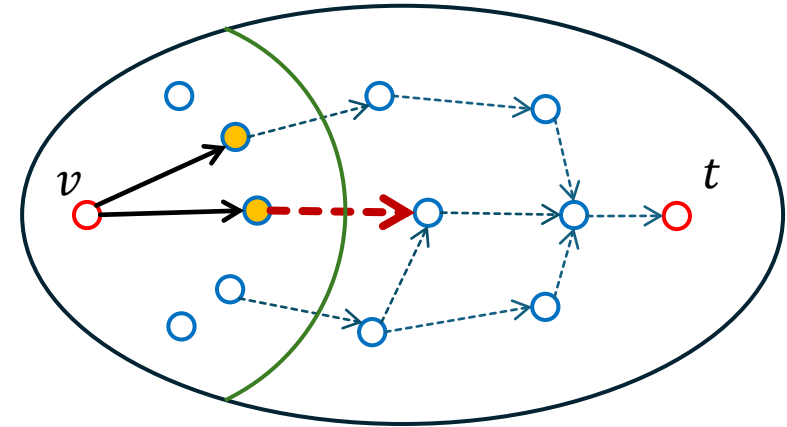


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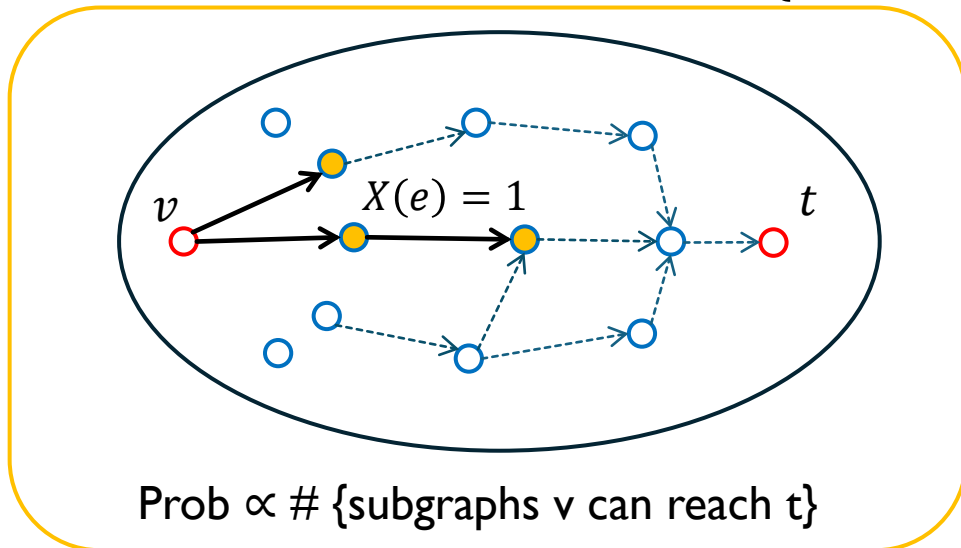
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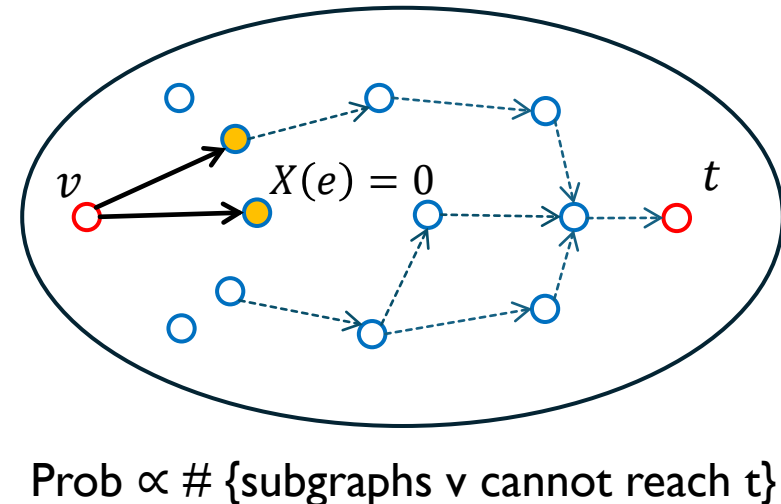


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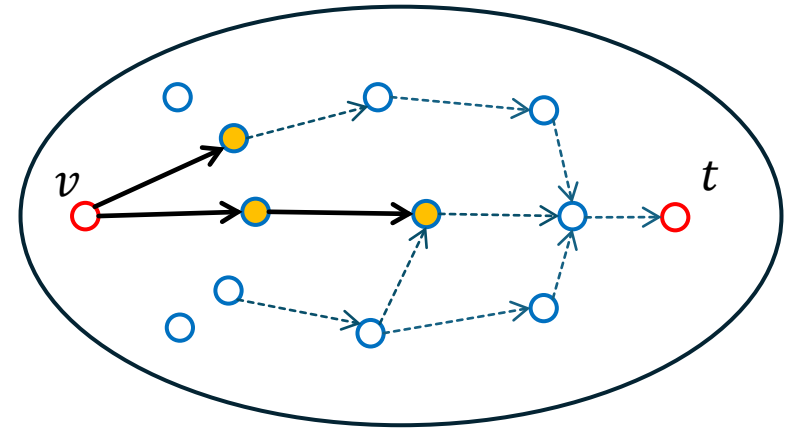
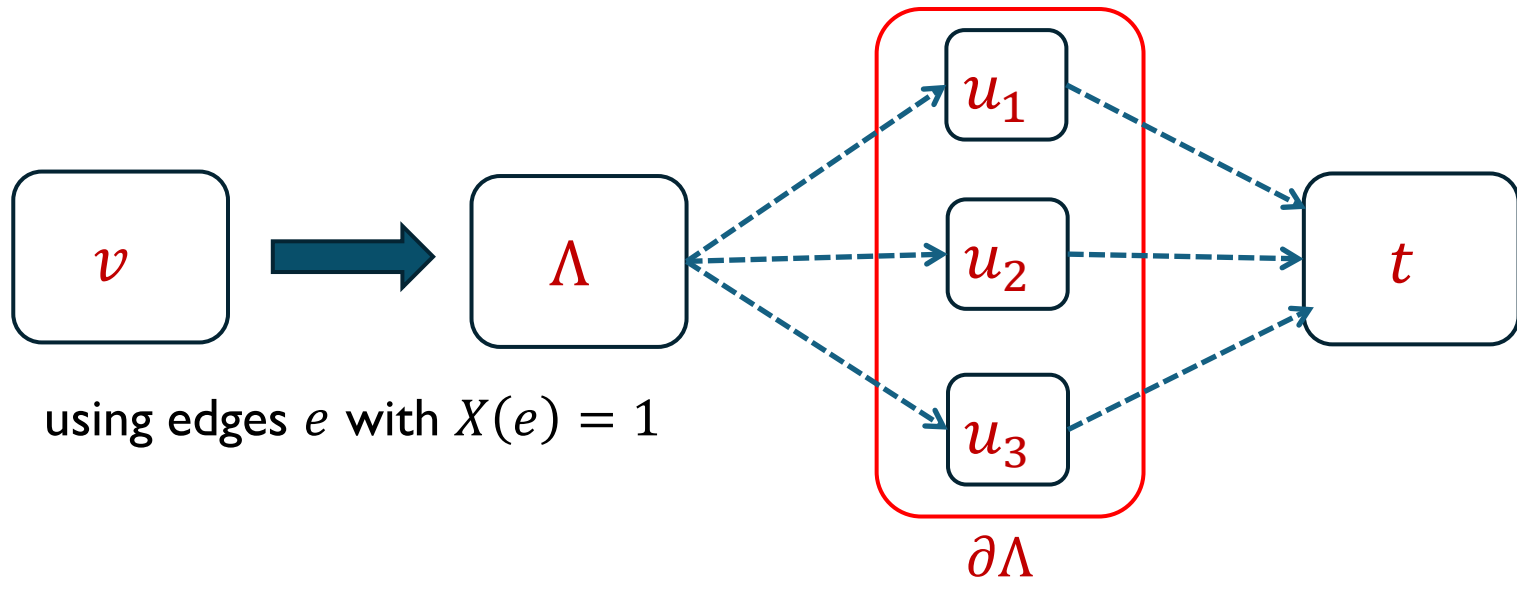
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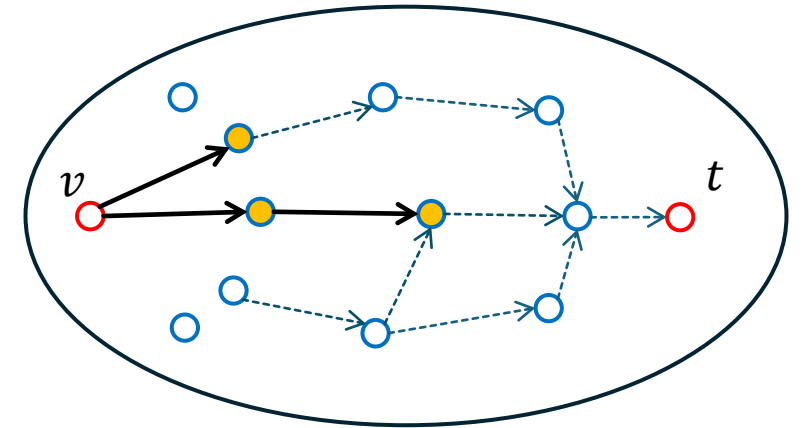
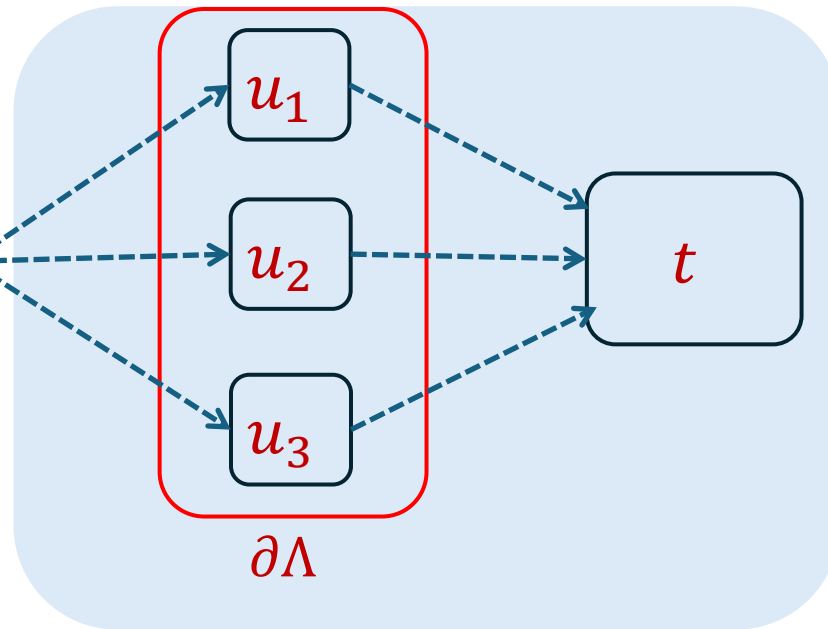
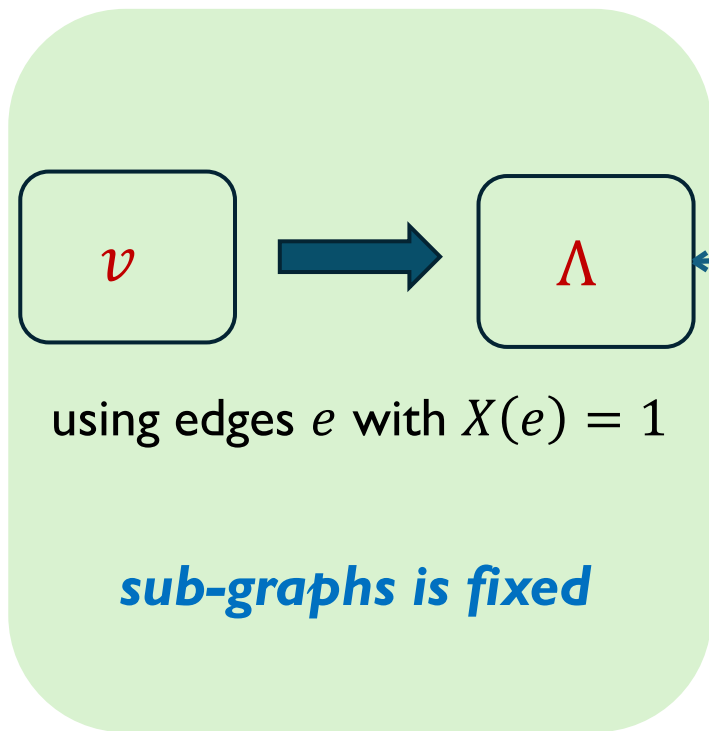


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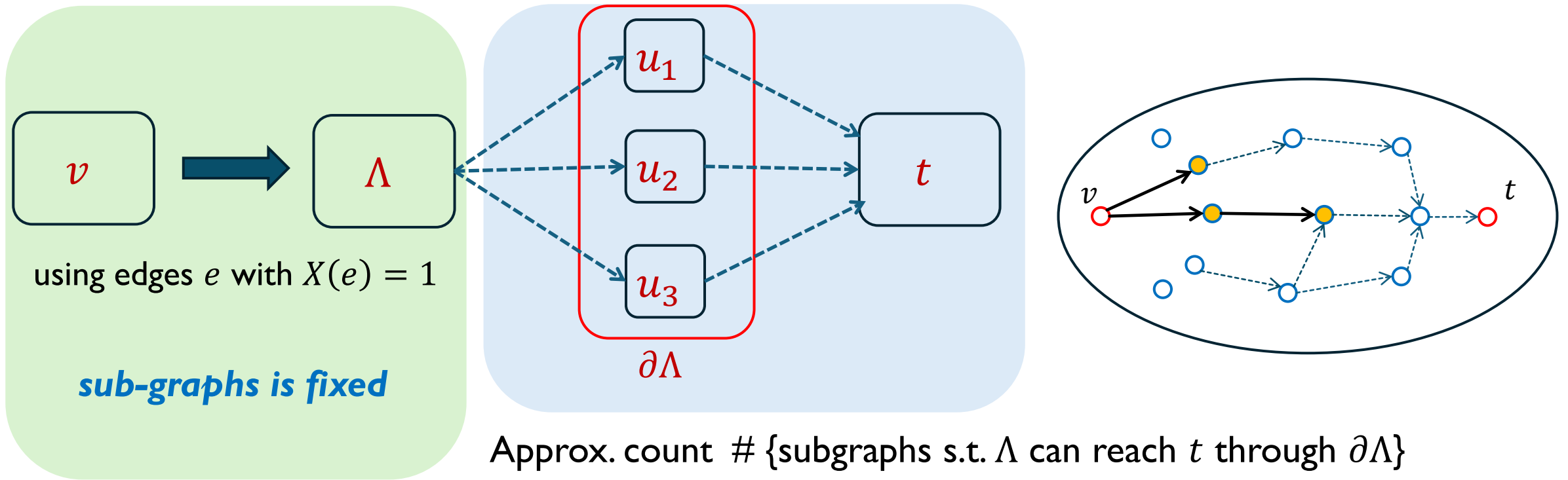






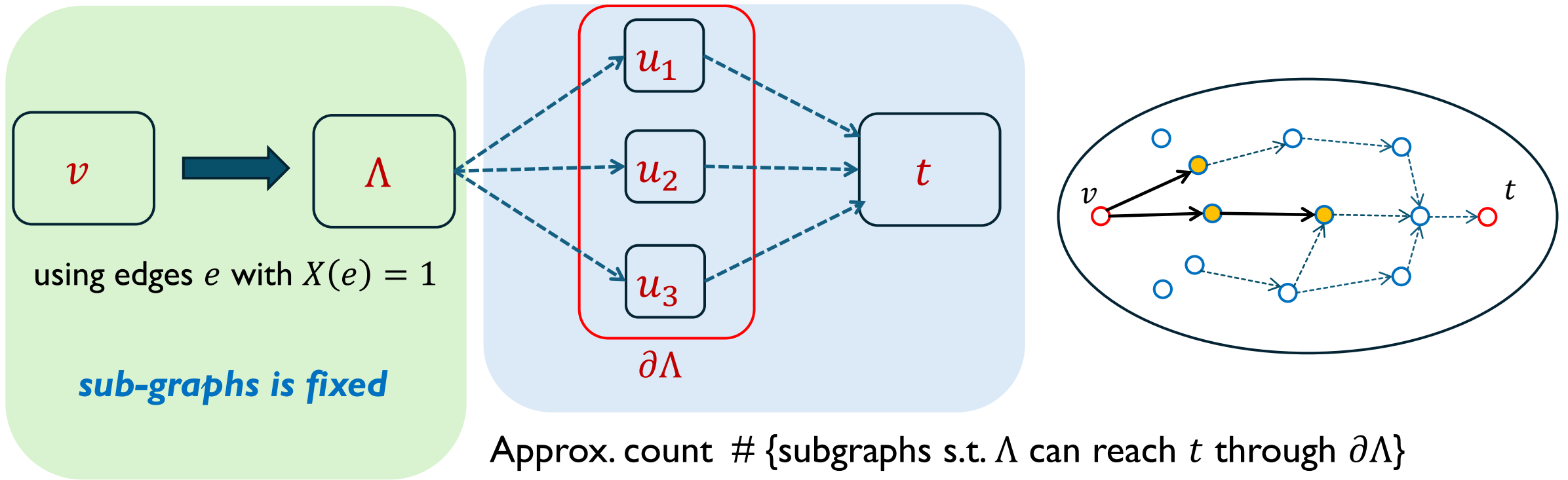


Approx. count  $\# \{ \text{subgraphs s.t. } \Lambda \text{ can reach } t \text{ through } \partial\Lambda \}$



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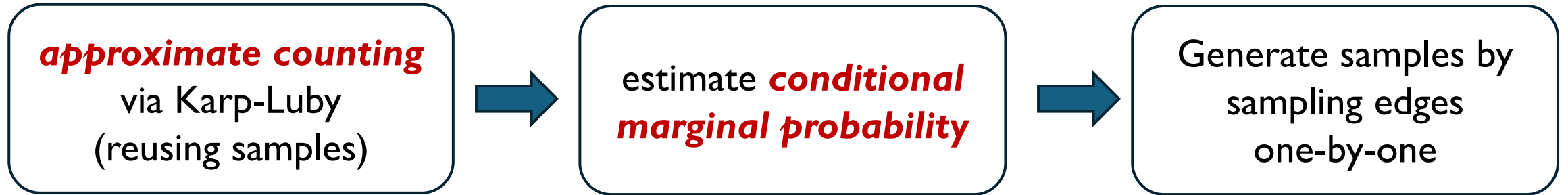
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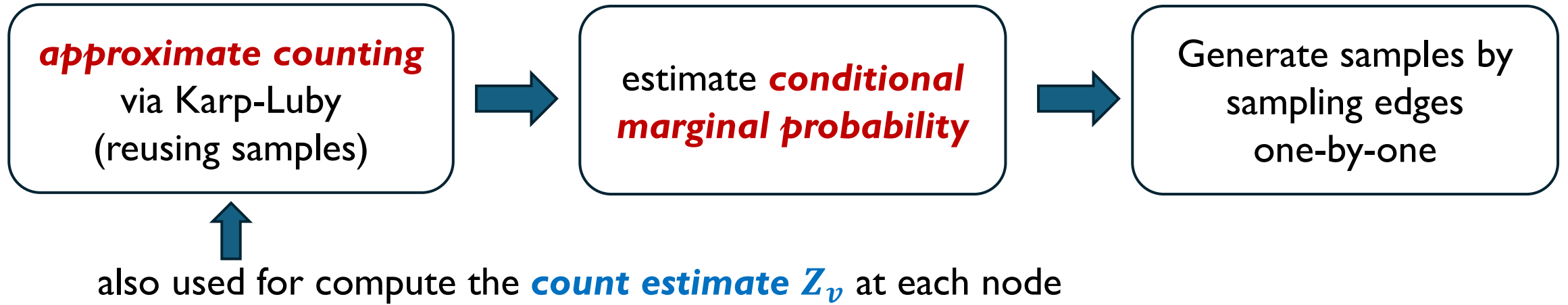
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- Run **Karp-Luby algorithm** by **reusing** the samples in nodes at  $\partial\Lambda$

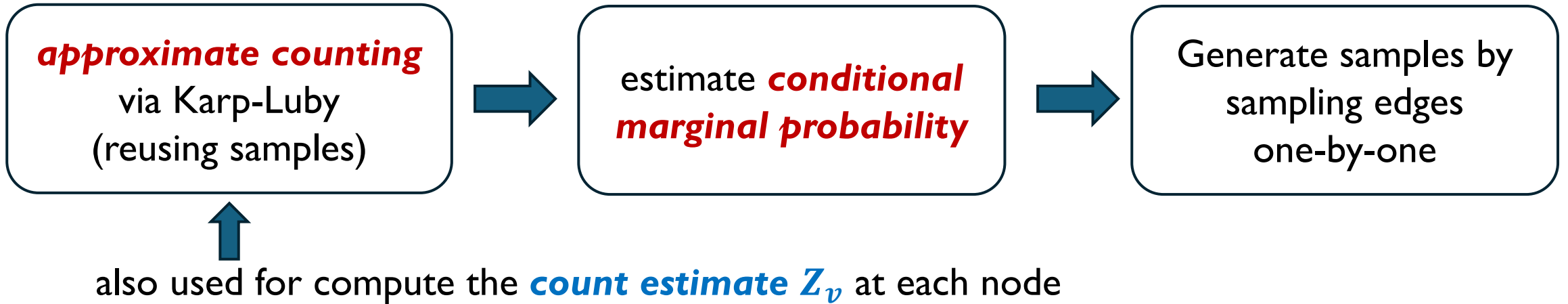
## Sampling Algorithm at Each Node



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- Sort all vertices in topological ordering  $t = v_1 < v_2 < \dots < v_n = s$
- $G_v$ : subgraph containing all vertices that can be reached from  $v \in V$   
 $\Omega_v = \{\text{subgraphs of } G_v \text{ such that } v \text{ can reach } t\}$
- $Z_v$ : a **count estimate** of the size  $\#\Omega_v$
- $S_v$ : a set of **samples**, where each  $H \in S_v$  is **uniform random sample** from  $\Omega_v$

# High-level analysis of the algorithm

**Challenge:** *reusing* samples introduces complicated *correlations*

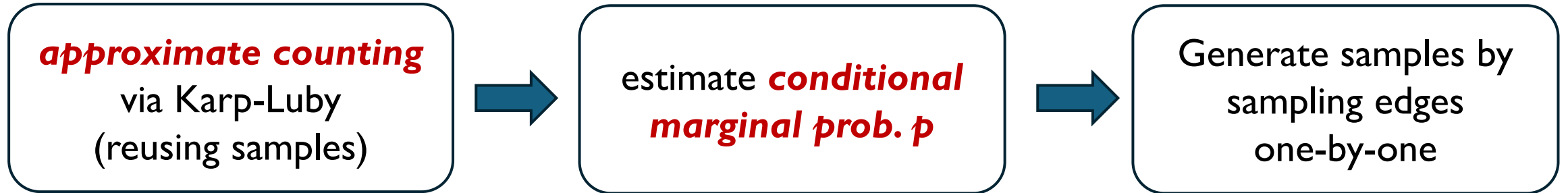
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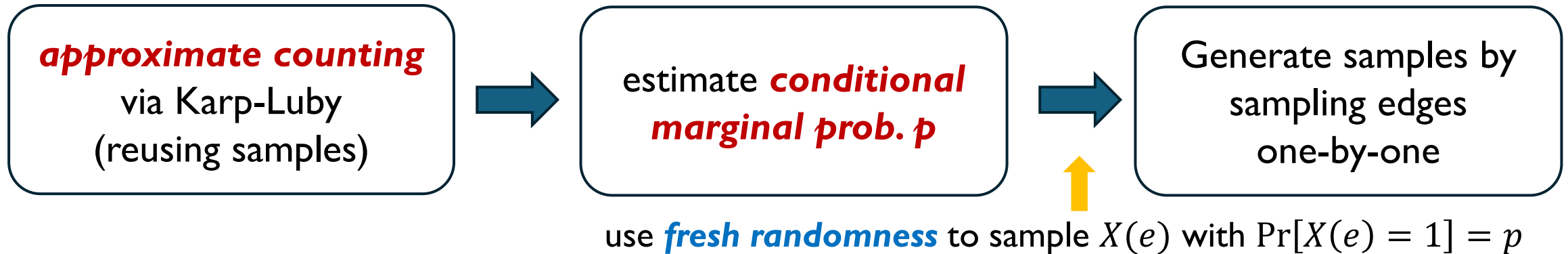
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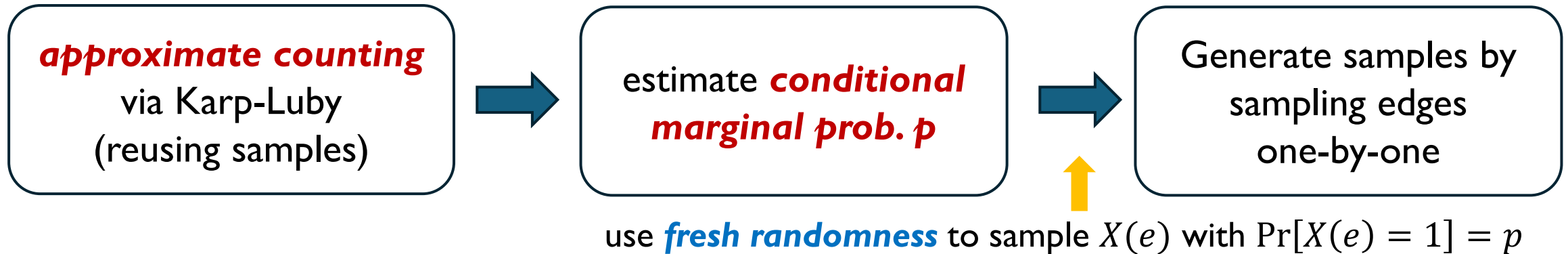
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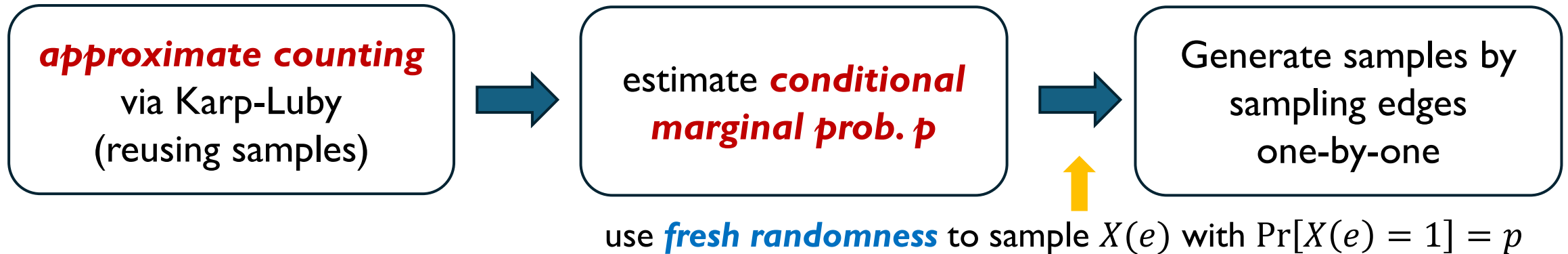
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- Conditional on estimate is correctly only bias random samples with *exp-small* error
- Show the whole algorithm is correct by an *induction proof*

# Open Problems

- **Faster** algorithm for s-t reliability in DAGs
- **Simple** algorithm for s-t reliability in DAGs
- FPTAS (**deterministic**) algorithm for s-t reliability in DAGs

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Thank you  
Q&A